2nd Workshop on Power-Aware Computing 2017

Domain Knowledge Specification for Energy Tuning

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Project Overview

• READEX:

Runtime Exploitation of Application Dynamism for Energy-efficient eXascale Computing

- Starting Date: 1 September 2015
- Duration:

3 years

• Funding

European Commission Horizon 2020 grant agreement 671657

• Collaboration with 6 other institutions all over Europe





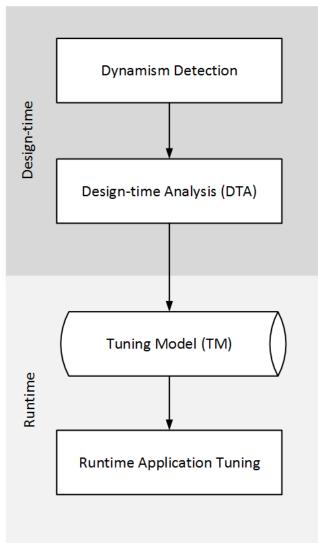
READEX Objectives

- Tuning HPC applications dynamically for energy efficiency.
- Improve energy efficiency by influencing tuning parameters
- Switching between configurations
 - Exploit dynamic characteristics
- Develop tool aided auto-tuning methodology.
 - Design-time Analysis
 - Runtime Application Tuning
- Detect at design-time, exploit at runtime.
- Compute better configuration
 - Specify domain knowledge by application owners
 - Identifiers
 - Application Tuning parameter





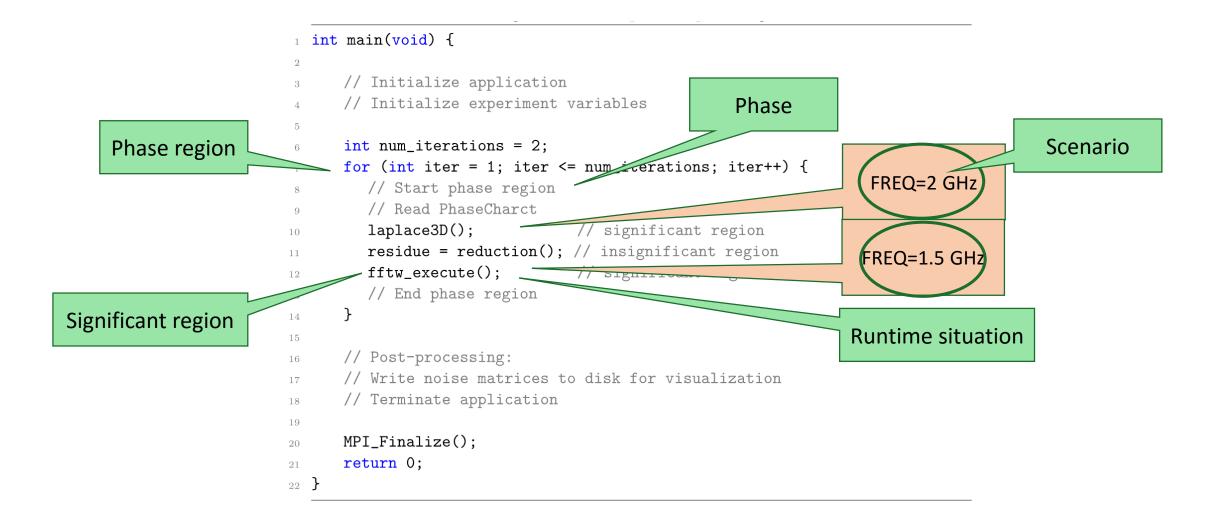
The READEX Tool Suite







Terminology: Phase Region and Phase

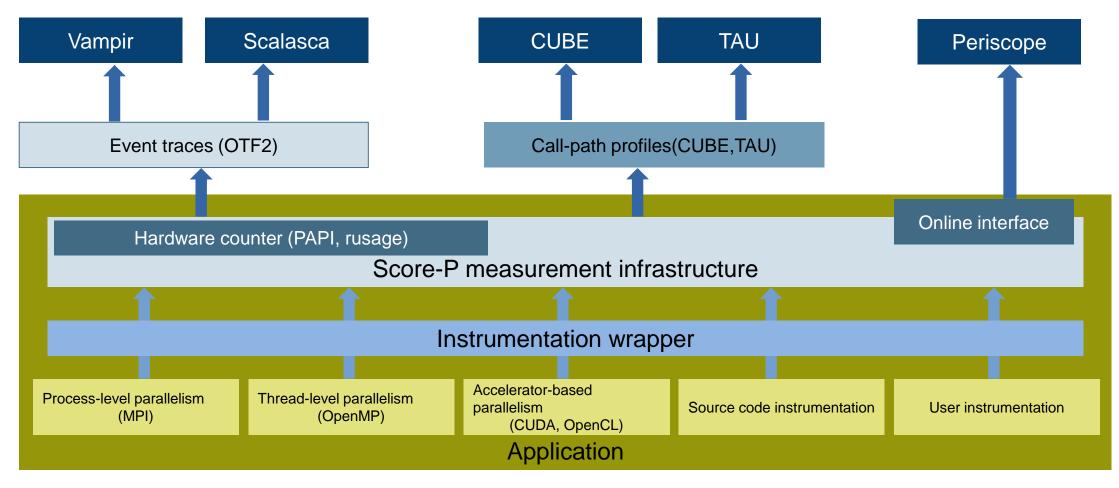






Score-P

- Scalable Performance Measurement Infrastructure for Parallel Codes
 - Common instrumentation and measurement infrastructure



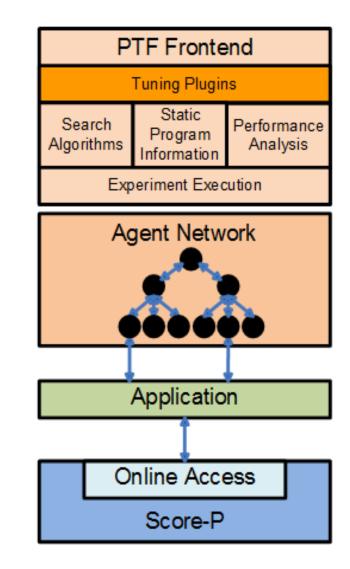




Periscope Tuning Framework (PTF)

Automatic application analysis & tuning

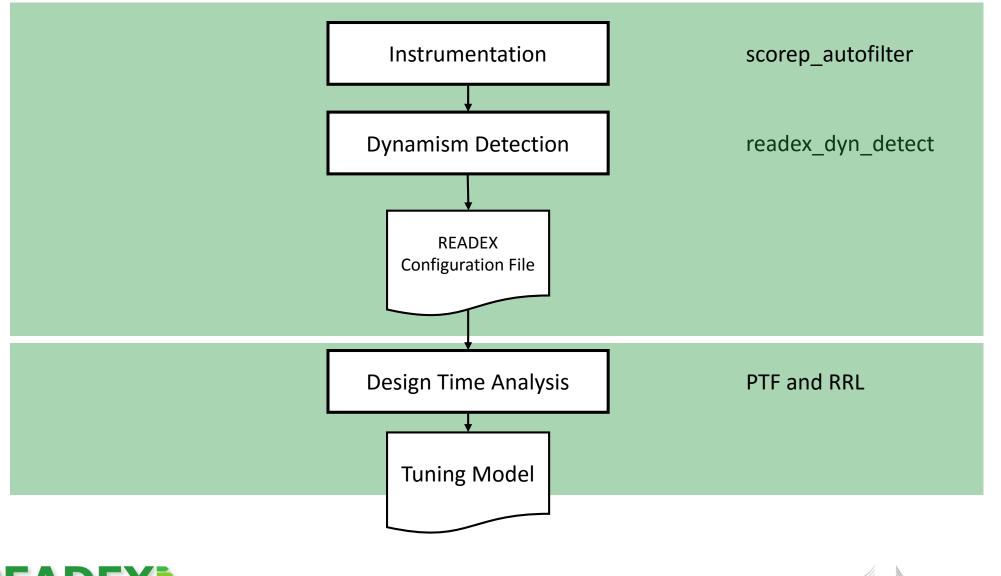
- Tune performance and energy (statically)
- Plug-in-based architecture
- Evaluate alternatives online
- Scalable and distributed framework Support variety of parallel paradigms
- MPI, OpenMP, OpenCL, Parallel pattern Developed in the AutoTune EU-FP7 project







Design Time Analysis





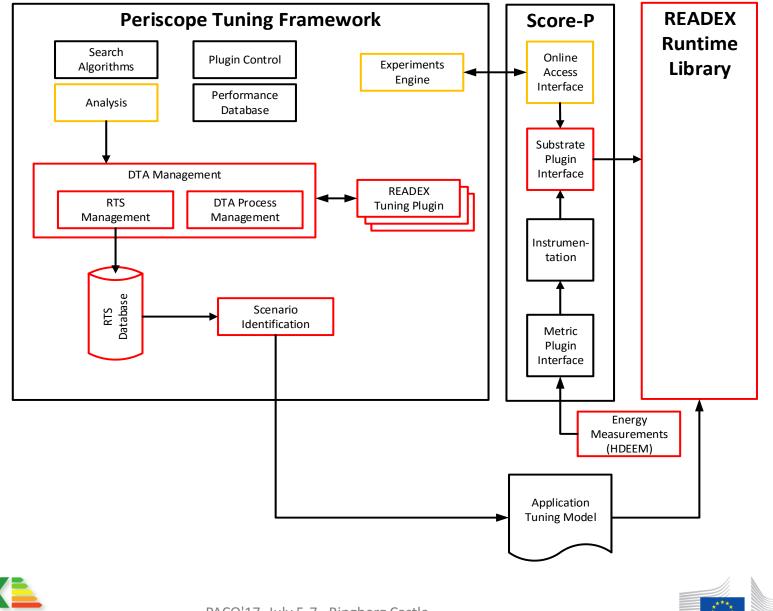


READEX Tuning Plugin

- Tuning plugin supporting
 - Core and uncore frequencies, numthreads parameters
 - Configurable search space via READEX Configuration File
 - Several objective functions: energy, CPUenergy, EDP, EDP2, time
 - Several search strategies: exhaustive, individual, random, genetic
- Approach
 - Experiment with default configuration
 - Experiments for selected configurations
 - Configuration set for phase region
 - Energy and time measured for all runtime situations
 - Identification of static best for phase and specific best configurations for rts's



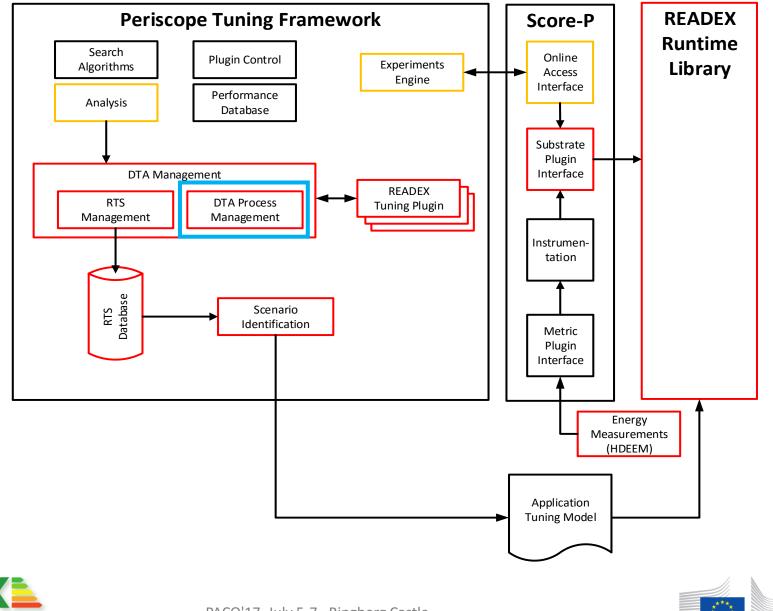




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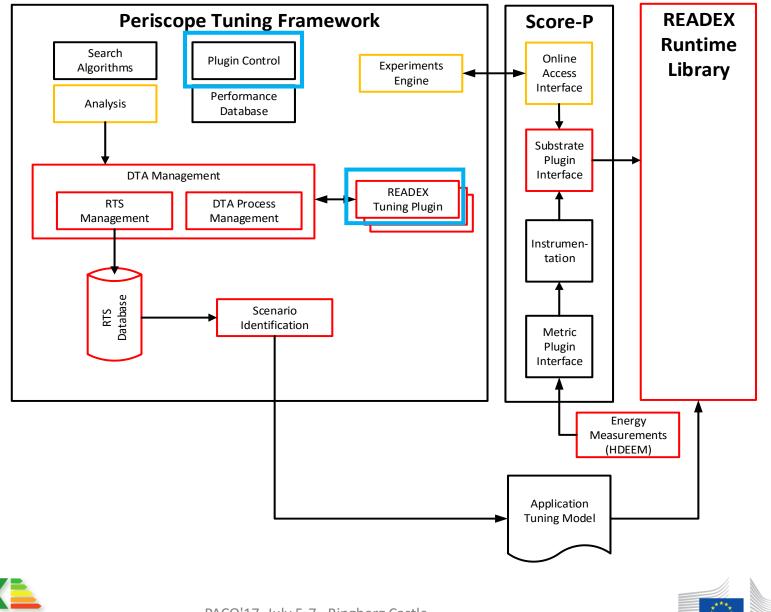




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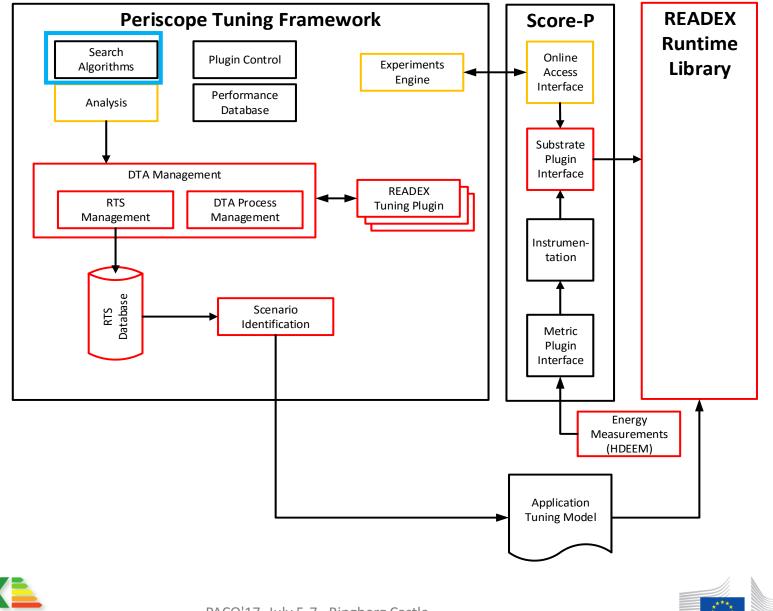




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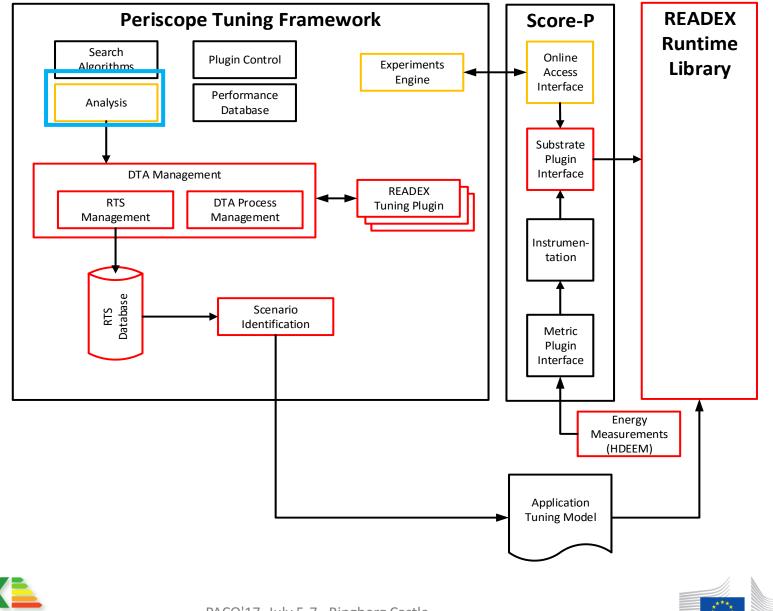




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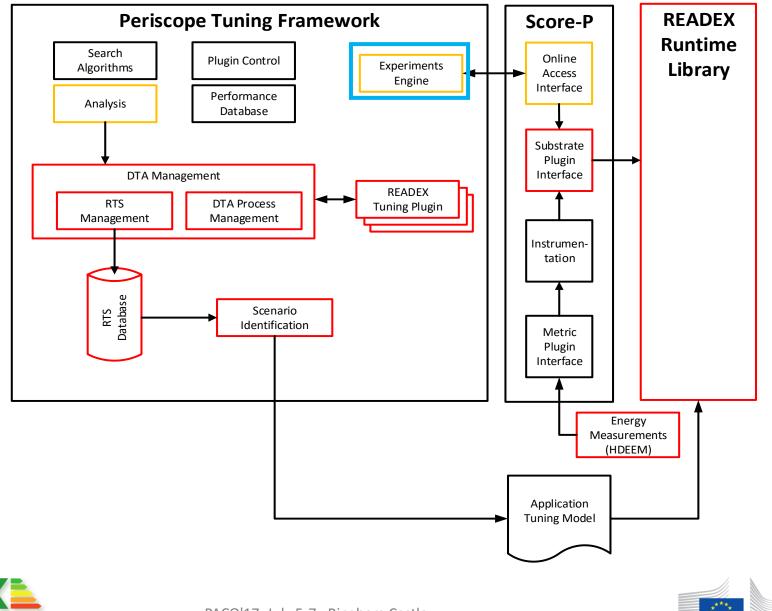




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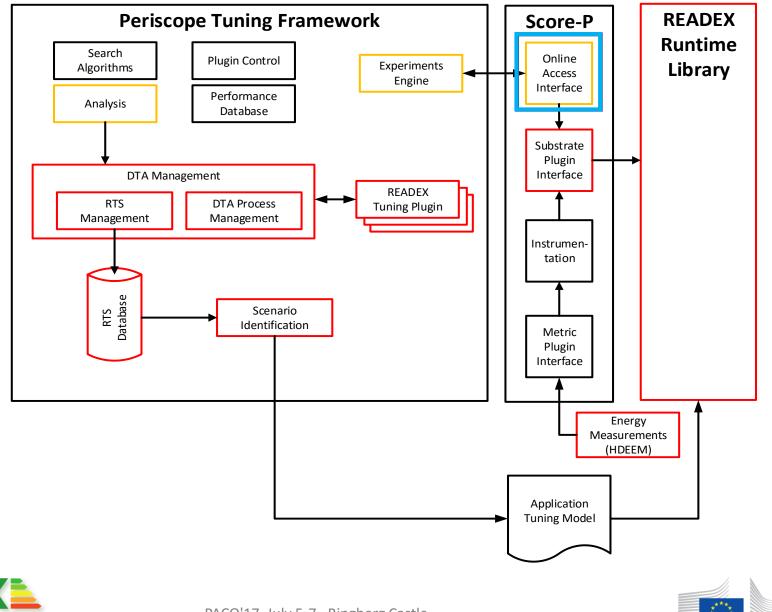




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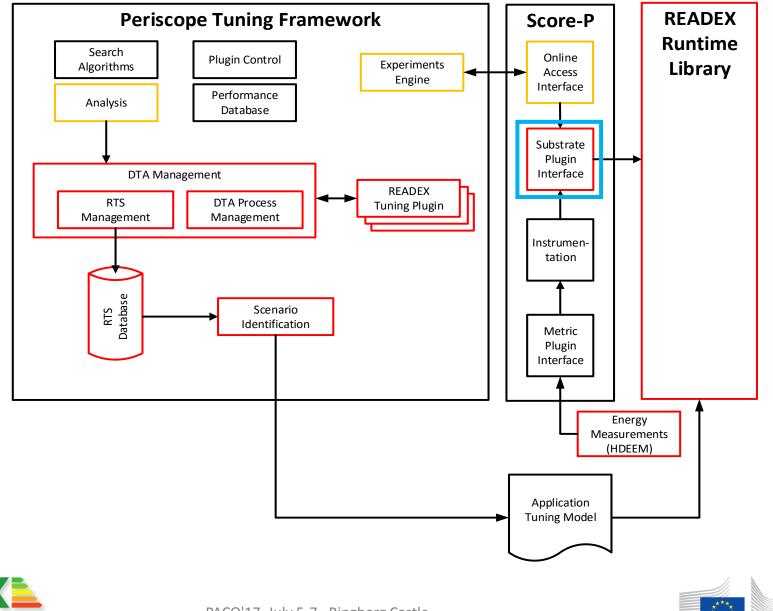




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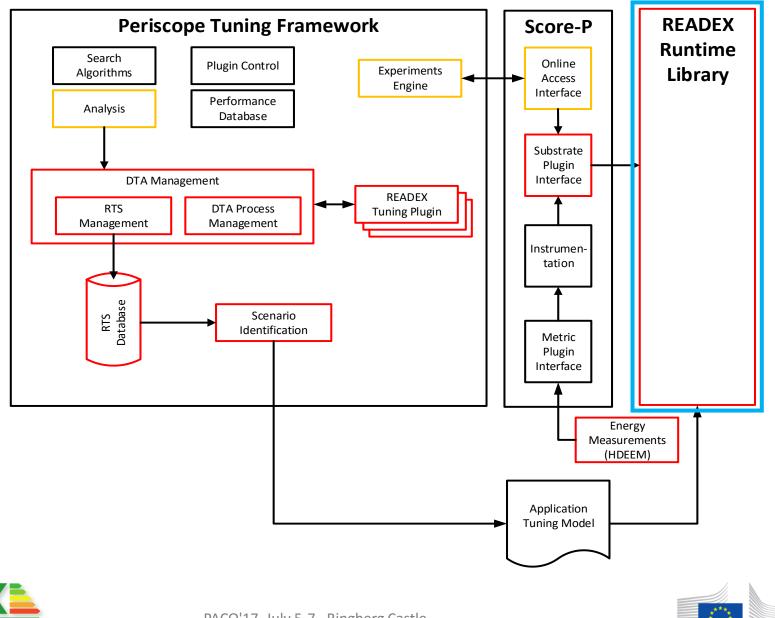




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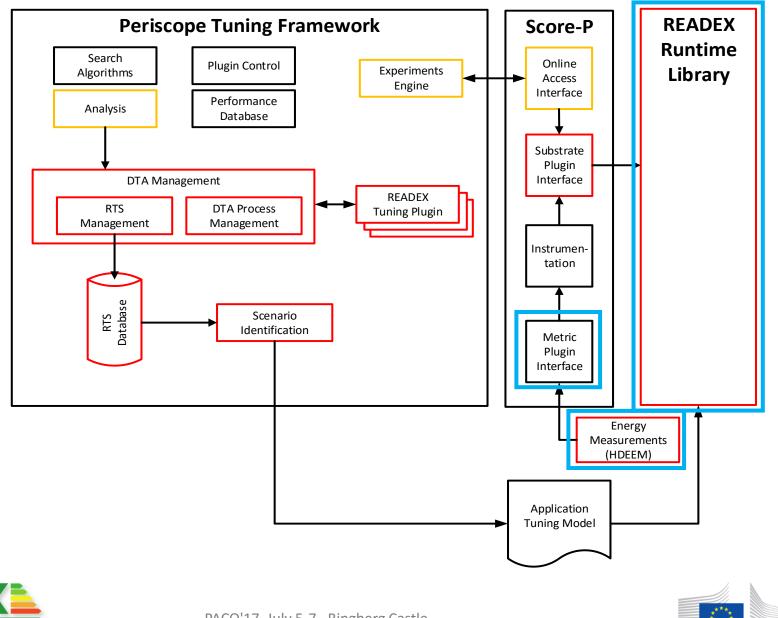




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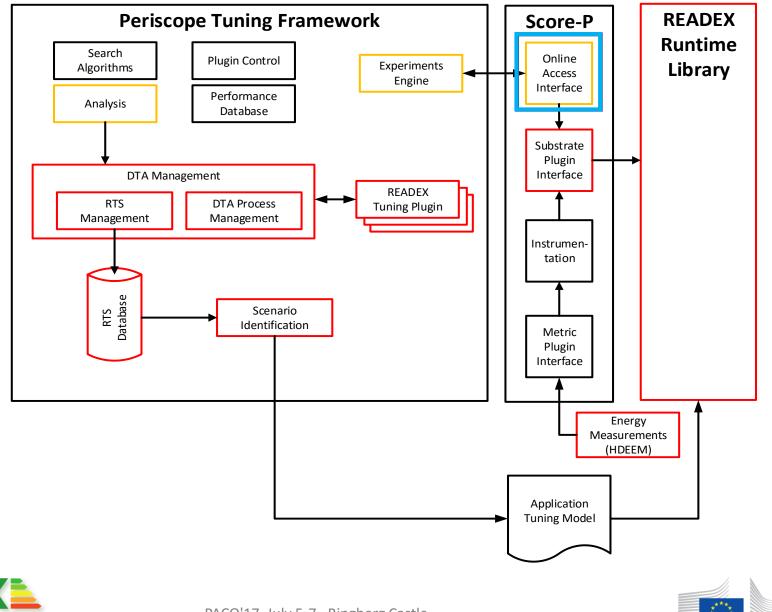




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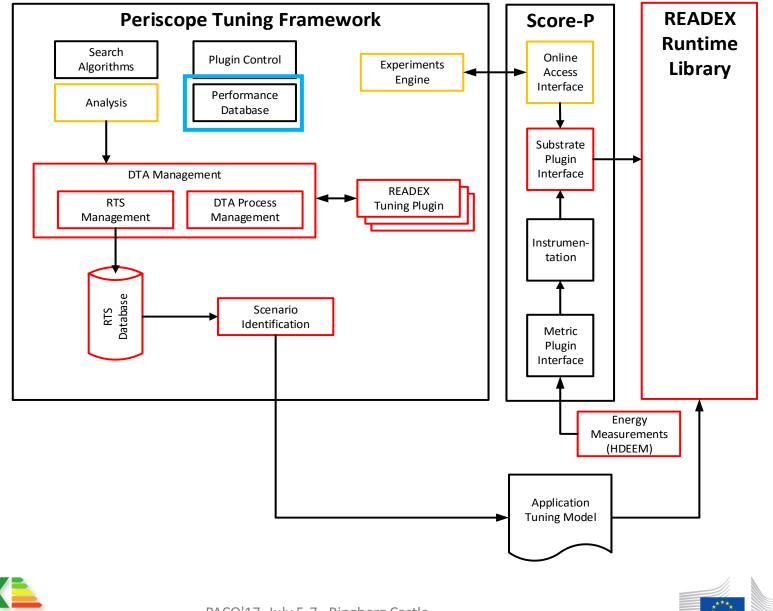




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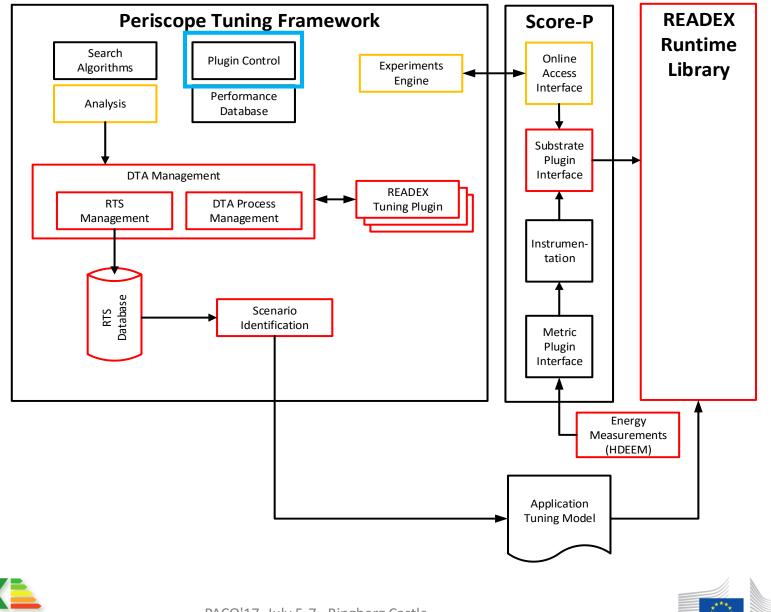




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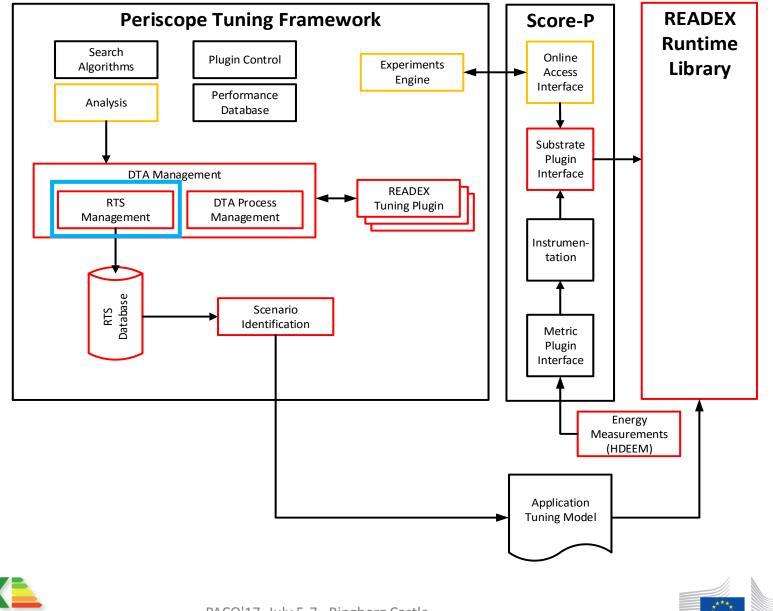




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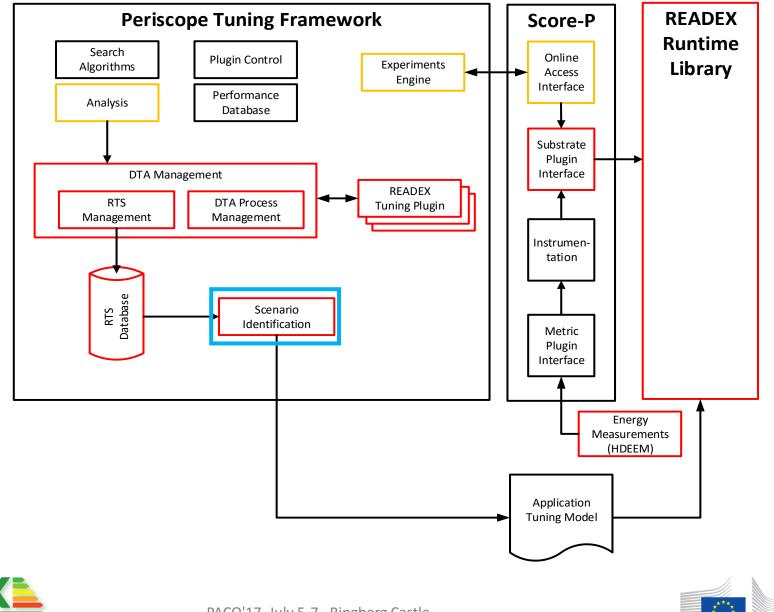




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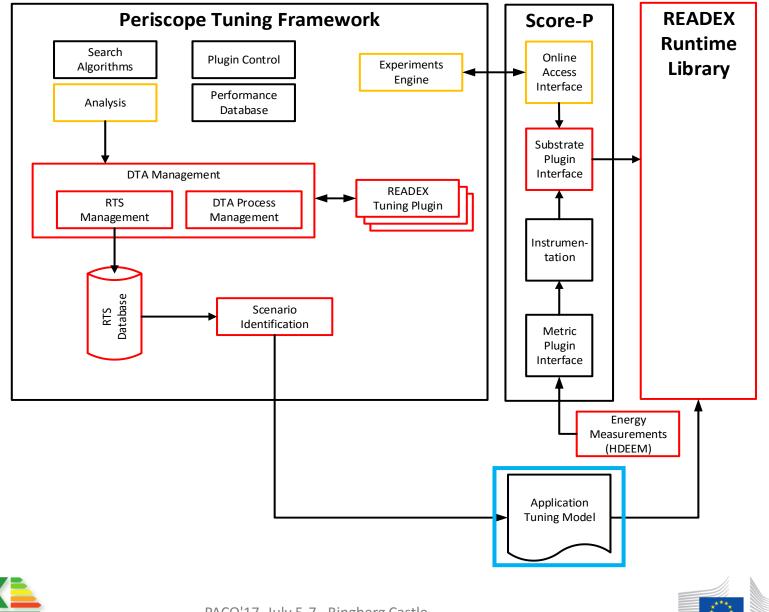




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Domain Knowledge Specification

- Improve tuning model
 - Distinguish more rts's
- So-called *Identifiers* to compute better system configurations
 - rts's
 - Region identifiers
 - Phase characteristics across phases
 - Phase identifiers
 - Executions with different application inputs
 - Input identifiers
- Application Tuning Parameter (ATP)
 - Switch application control flow





Identifier Specification- region identifiers

- Specify identifiers via Score-P user parameter
 - Identify different characteristics in rts's
- *Interpolate* the minimum grid level to the maximum
 - Computation switches from compute bound to memory bound
 - For DTA
 - determine special system configurations for compute and memory bound rts's
 - Add a region identifier to code for the grid level
 - Region name, call path and region identifier are used as identifiers.

Listing: Region Identifiers

!--- level k-1 to level k ---!

do k = min_level+1,max_level
 call interpolate(...,k)
 call resid(...)
 call psinv(...)
end do

```
!--- Interpolate to level k region ---!
subroutine interpolate(...,k)
SCOREP_USER_PARAMETER("level", k)
```

end subroutine

. . .





Identifier Specification- phase and input identifiers

Phase Identifiers

• Exploit dynamism of the application across phases

Input Identifiers

- Improve tuning model
 - Identify system configurations for different inputs characteristics.
- Example:
 - Grid level computation switches from compute to memory bound
 - depends on the resolution of the finest grid and the number of MPI processes.
 - The finer the grid, the more levels are memory bound.
 - The more processes are used, the fewer levels are memory bound due to an increased amount of cache.





Application Tuning Parameters (ATP)

- exploit the dynamism
 - through the use of different code paths (e.g. preconditioners)
- Identify the control variables responsible for control flow switching.
 - provides APIs to annotate the source code





Motivational ATP Example (Espreso)

- Finite Element (FEM) tools and domain decomposition based Finite Element Tearing and Interconnect (FETI) solvers.
- FETI Solver
 - contains a projected conjugate gradient (PCG) solver.
 - Convergence can be improved by several preconditioners.
- Evaluated preconditioners on a structural mechanics problem with 23 million unknowns
 15.9 s 4091.5 j
 - On a single compute node with 24 MPI processes.

Preconditioner	# iterations	1 iteration		Sclution	
None	172	125 ms	31.6 J	21.36 s	5 501.31 J
Weight function	100	130+2 ms	32.3+0.53 J	12.89 s	3 284.07 J
Lumped	45	130+10 ms	32.3+3.86 J	6.32 s	1 636.11 J
Light dirichlet	39	130+10 ms	32.3+3.74 J	5.46 s /	1 409.82 J
Dirichlet	30	130+80 ms	32.3+20.62 J	6.34 s	1 594.50 J



Conclusion

- Aim to improving the energy efficiency of HPC applications by a dynamic tuning approach.
- At design time, tuning parameters is determined
 - tuning model guides the dynamic switching
- Tuning model enhanced
 - domain knowledge that is provided by the application owner.
- To know more about the project, go to http://www.readex.eu/





Discussion





European Commission